

# Heat eqn.

therm. energy in  $\Omega = \iint_{\Omega} \rho c u \, dA$   
temp.

heat flux =  $-k \nabla u$  (Fourier)

change of therm. energy = - total outflux

$$\frac{d}{dt} \left( \iint_{\Omega} \rho c u \, dA \right) = - \int_C (-k \nabla u) \cdot d\vec{N}$$

//

$$\iint_{\Omega} \rho c \frac{\partial u}{\partial t} \, dA \stackrel{\text{Green}}{=} \iint_{\Omega} \nabla \cdot (k \nabla u) \, dA$$

$$\left( \begin{aligned} \nabla \cdot \vec{B} &= \frac{\partial B_1}{\partial x} + \frac{\partial B_2}{\partial y} \\ \vec{B} &= \begin{pmatrix} B_1 \\ B_2 \end{pmatrix} \end{aligned} \right)$$

$$\rightarrow \iint_{\Omega} \left( \rho c \frac{\partial u}{\partial t} - k \nabla \cdot (\nabla u) \right) dA = 0$$

$\xrightarrow{\text{arb. } \Omega}$

$$\frac{\partial u}{\partial t} = \frac{k}{\rho c} \nabla \cdot (\nabla u) \quad \nabla u = \begin{pmatrix} \frac{\partial u}{\partial x} \\ \frac{\partial u}{\partial y} \end{pmatrix}$$

Using:

$$\nabla \cdot (\nabla u) = \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \end{pmatrix} \cdot \begin{pmatrix} \frac{\partial u}{\partial x} \\ \frac{\partial u}{\partial y} \end{pmatrix} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \Delta u$$

$(\Delta = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2})$

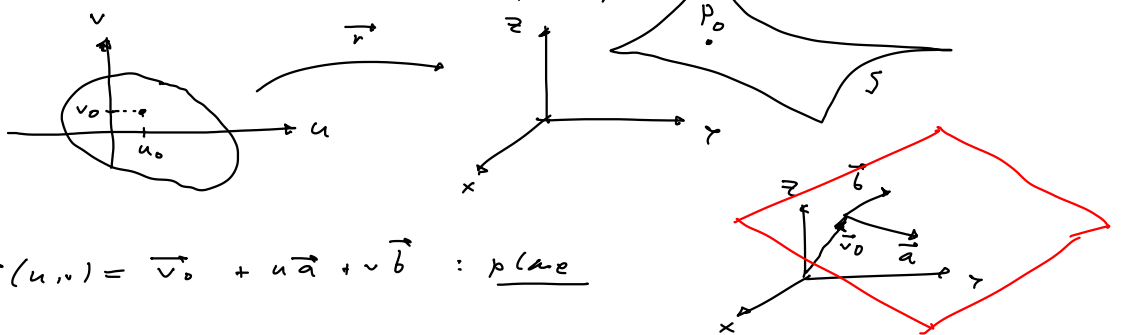
$$\rightarrow \boxed{\frac{\partial u}{\partial t} = \frac{k}{\rho c} \Delta u} \quad \text{Heat eqn.}$$

Static case: no time dependence  $\rightarrow \boxed{\Delta u = 0}$

$$\left[ \nabla^2 = \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \end{pmatrix} \cdot \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \end{pmatrix} = \dots \right] \quad \text{Laplace eqn.}$$

## Recap:

Surface:  $\vec{r}: D \rightarrow \mathbb{R}^3$   
 $(u, v) \mapsto \vec{r}(u, v) = \begin{pmatrix} f(u, v) \\ g(u, v) \\ h(u, v) \end{pmatrix}$   $P_0 = \vec{r}(u_0, v_0)$



$\underline{\text{Ex:}}$   $\vec{r}(u, v) = \vec{v}_0 + u \vec{a} + v \vec{b}$  : plane

Ex: Surface of revolution

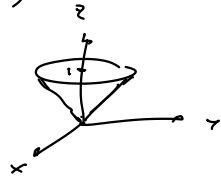
$$\vec{r}: [0, 1] \rightarrow \mathbb{R}^3$$

$$u \mapsto \vec{r}(u) = \begin{pmatrix} u \\ 0 \\ u \end{pmatrix}$$

Then:

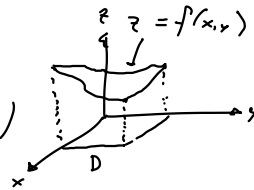
$$\vec{r}(u, v) = \begin{pmatrix} \cos(v) & -\sin(v) & 0 \\ \sin(v) & \cos(v) & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} u \\ 0 \\ u \end{pmatrix}$$

$$= \begin{pmatrix} u \cos(v) \\ u \sin(v) \\ u \end{pmatrix} : \text{cone}$$



Graphs: Let  $f(x, y)$  be given.

→ The Graph  $z = f(x, y)$  describes the surface:  $(x, y) \mapsto (x, y, f(x, y))$



Surface area: Let  $\vec{r}(u, v)$  be given.

$$\vec{r}: D \rightarrow \mathbb{R}^3$$

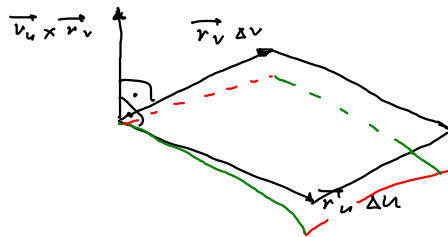
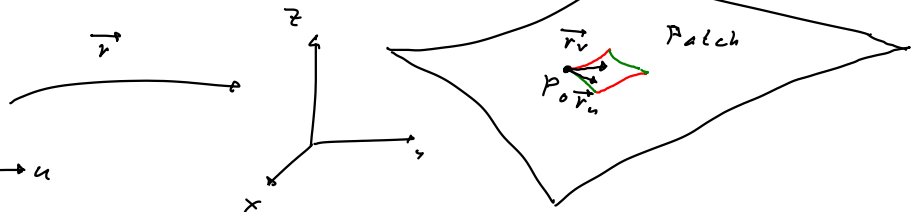
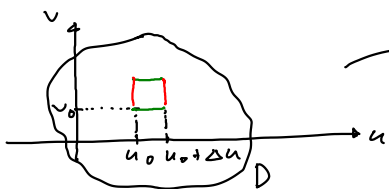
$$(u, v) \mapsto \vec{r}(u, v)$$

$$A = \iint_D |\vec{r}_u \times \vec{r}_v| \, du \, dv$$

integral over parameter domain D

$$\left( \vec{r}_u = \frac{\partial \vec{r}}{\partial u} ; \vec{r}_v = \frac{\partial \vec{r}}{\partial v} \right)$$

Interpretation:



$$\Delta A \cong |\vec{r}_u \Delta u \times \vec{r}_v \Delta v|$$

$$= |\vec{r}_u \times \vec{r}_v| \Delta u \Delta v$$

$$A \cong \sum \Delta A$$

$$\rightarrow A = \iint_D |\vec{r}_u \times \vec{r}_v| \, du \, dv$$

Surface integrals

(i) of scalar functions

Def: Let  $f: \mathbb{R}^3 \rightarrow \mathbb{R}$  be a scalar field. Then the surface integral of  $f$  over  $S$  is:

$$\iint_S f \, dS = \iint_D f(\vec{r}(u, v)) |\vec{r}_u \times \vec{r}_v| \, du \, dv$$

Ex:  $f = \rho$  with  $\rho$  defined only on the surface  $S$  and:  $\rho(x, y, z)$ : mass per unit area.

$$\rightarrow \iint_S \rho \, dS = \iint_D \rho(\vec{r}(u, v)) |\vec{r}_u \times \vec{r}_v| \, du \, dv = \text{Mass.}$$

(ii) of vector fields:

Def: Let  $\vec{F}: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  be a vector field. Then the surface integral of  $\vec{F}$  over  $S$  is:

$$\iint_S \vec{F} \cdot d\vec{S} = \iint_S \vec{F} \cdot \vec{N} \, dS, \quad \text{surf. int. of the scalar field } \vec{F} \cdot \vec{N}$$

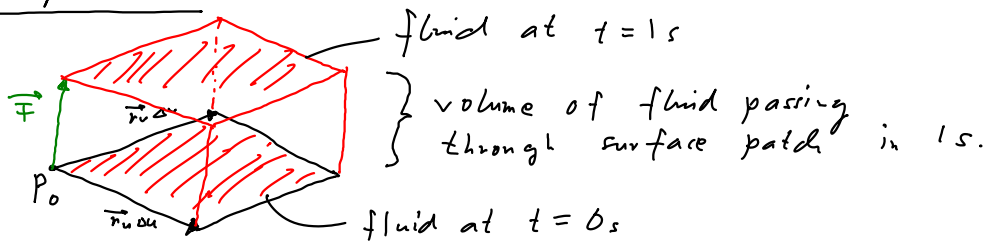
where  $\vec{N}$  is the unit normal vector to  $S$ .

We have:

$$\vec{N} = \frac{\vec{r}_u \times \vec{r}_v}{|\vec{r}_u \times \vec{r}_v|}$$

$$\begin{aligned} \iint_S \vec{F} \cdot d\vec{S} &= \iint_S \vec{F} \cdot \vec{N} \, dS \\ &= \iint_D \vec{F} \cdot \frac{\vec{r}_u \times \vec{r}_v}{|\vec{r}_u \times \vec{r}_v|} |\vec{r}_u \times \vec{r}_v| \, du \, dv \\ &= \iint_D \vec{F} \cdot (\vec{r}_u \times \vec{r}_v) \, du \, dv \end{aligned}$$

Interpretation:



Let  $\vec{F}$  be velocity field  $|\vec{F}| = 17$

i.e. at  $P_0$ , the fluid speed is 17 m/s

$\rightarrow$  Fluid passing through patch in 1s:

$$\begin{aligned} \Delta \text{Flux} &= \vec{F} \cdot (\vec{r}_u \, \Delta u \times \vec{r}_v \, \Delta v) \\ &= \vec{F} \cdot (\vec{r}_u \times \vec{r}_v) \, \Delta u \, \Delta v \end{aligned}$$

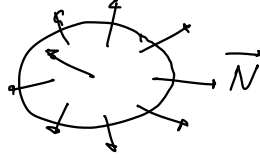
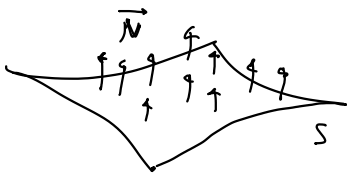
$\rightarrow$  total flux:  $\iint_D \vec{F} \cdot (\vec{r}_u \times \vec{r}_v) \, \Delta u \, \Delta v$

I.e.

$$\boxed{\iint_S \vec{F} \cdot d\vec{S} = \text{Flux}}$$

Remark: Orientation

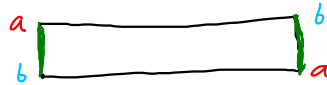
We call a surface  $S$  orientable (or two-sided) if it is possible to define a field  $\vec{N}$  of unit normal vectors that varies continuously with position.



Convention: For closed surface (e.g. sphere) we take  $\vec{N}$  to point outward.

Ex: Non orientable surface:

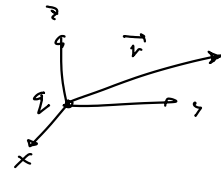
Möbius strip: piece of paper:



glue green on green with corners a-a, b-b together.

Ex: Flux of electric field of point charge  $q$  through sphere of radius  $R$ :

$$\vec{E}(\vec{r}) = \frac{q}{4\pi\epsilon_0} \frac{\vec{r}}{|\vec{r}|^3} \quad \vec{r} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$



$$\begin{aligned} \text{Flux} &= \iint_S \vec{E} \cdot d\vec{S} \\ &= \iint_S \vec{E} \cdot \vec{N} ds \end{aligned}$$



$$\begin{aligned} &= \iint_S |\vec{E}| ds \\ &= \iint_S \frac{q}{4\pi\epsilon_0 R^2} ds = \frac{q}{4\pi\epsilon_0 R^2} \underbrace{\iint_S ds}_{= 4\pi R^2} = \frac{q}{\epsilon_0} \end{aligned}$$